NEW

AutoTracker Guide

The new version of AutoTracker run all the same calculations as the previous version while introducing refinements that streamline use, improve processing speed, and minimize errors.

# Importing

The new AutoTracker code is now formatted as Python module so it can be easily imported into any Jupyter Notebook. To import the AutoTracker, run the code below.

|  |
| --- |
| from hilllab.autotracker import \* |

# Loading Files

File paths are chosen using the function below. It opens a dialog to select a directory containing videos and another dialog to choose where to save the VRPN files. It also prints a summary so you can verify your selections.

|  |
| --- |
| video\_path, save\_path = autotrack\_select\_paths() |

The **video\_path** and **save\_path** arguments returned from this function can then be passed directly into the main AutoTracker function.Autotracking

The AutoTracker runs using the function below, which accepts various arguments to adjust the tracking process.

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| --- |
| autotrack\_videos() |

## ARGUMENTS

* **video\_path** (string): the path to the folder containing the videos.
* **save\_path** (string): the path to the folder where outputs should be saved.
* **bead\_size\_pixels** (int, optional): the estimated diameter of the particles in pixels. Default is 21.
* **trajectory\_fraction** (float, optional):the minimum fraction of frames in which a particle must appear to be included in the track. A value of 1.0 requires appearance in every frame, while 0.5 requires appearance in half of the frames. Default is 1.0.
* **max\_travel\_pixels** (int, optional): the maximum distance (in pixels) a particle can move between consecutive frames to be considered the same particle. Defaults to 5.
* **memory** (int, optional): the maximum number of frames during which a particle can vanish, then reappear nearby, and be considered the same particle. Defaults to 0.
* **invert** (bool, optional): when set to true, the AutoTracker searches for dark particles on a light background instead of light particles on a dark one. Defaults to false.
* **performance\_mode** (“safe”, “slow”, or “fast”, optional): determines how many CPU processes the AutoTracker can use. A value of “safe” uses most available cores while leaving some for background tasks, “slow” uses half of the cores, and “fast” uses all cores. Default is “safe.”

Once running, the AutoTracker saves VRPN files to the selected location. If it encounters certain errors while processing a video, it will skip that video and create a report in the video’s folder describing the issue.

# **VRPN Structure**

Data from the AutoTracker is saved as MATLAB files with the .vrpn extension. All data is stored within a struct named **tracking**, and particle position data is stored in **spot3DSecUsecIndexFramenumXYZRPY**. This naming convention is retained for compatibility with legacy code but is not relevant to current versions.

This table lists the position of each particle for every frame in sequence, with columns organized as follows. Any column marked as not used is filled with zeros by default.

|  |  |
| --- | --- |
| **Column #** | **Value** |
| **1** | Seconds *(not used)* |
| **2** | Microseconds *(not used)* |
| **3** | Particle ID |
| **4** | Frame Number |
| **5** | X position (in pixels) |
| **6** | Y position (in pixels) |
| **7** | Z position *(not used)* |
| **8** | Roll *(not used)* |
| **9** | Pitch *(not used)* |
| **10** | Yaw *(not used)* |